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east interference search LDR 10/6/08
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EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	11	physical attribute of an object and fixing one or more cameras and fixing one or more fanned lasers and establish a mathematical spatial relationship and creating a pixelated image and selected at least one pixel and each of the selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship. clm.	US-PGPUB	NEAR	ON	2008/10/06 14:35
L2	11	physical attribute of an object and fixing one or more cameras and fixing one or more fanned lasers and establish a mathematical spatial relationship and creating a pixelated image and selected at least one pixel and each of the selected pixel locations same mathmatical spatial and using	US-PGPUB	NEAR	ON	2008/10/06 14:37

		the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.				
L3	0	physical attribute of an object and fixing one more cameras and fixing one more fanned lasers and establish a mathematical spatial relationship and creating a pixelated image and selected at least one pixel and each of the selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:38
L4	0	attribute of an object and fixing one more cameras and fixing one more fanned lasers and establish a mathematical spatial relationship and creating a pixelated image and selected at least one pixel and each of the	US-PGPUB	NEAR	ON	2008/10/06 14:39

		selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.				
L5	0	object and fixing one more cameras and fixing one more fanned lasers and establish a mathematical spatial relationship and creating a pixelated image and selected at least one pixel and each of the selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:39

L6	0	mathematical spatial relationship and creating a pixelated image and selected at least one pixel and each of the selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40
L7	0	pixel and each of the selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40
L8	0	each of the selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40

L9	0	selected pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40
L10	0	pixel locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40
L11	0	locations same mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40
L12	0	mathmatical spatial and using the three dimensional position and establishing a mathematical spatial relationship and six non-collinear visible markings.clm.	US-PGPUB	NEAR	ON	2008/10/06 14:40

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